





# Thermomechanical Measurements for Energy Systems (MENR)

## Measurements for Mechanical Systems and Production (MMER)

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#### Numerical & Digital instruments :

*Numerical* (and *digital*) *instruments* display the "measurement" information directly with *numbers* in *digit format* !



No mechanical indicator; No indication delay; No reading errors; ...



The first numerical indicators were *Light Emitting Diodes* (*LED*) made of *gallium arsenide* (GaS) and *gallium phosphide* (GaP) PN junctions directly polarized !

They use current and, therefore, they heat up ... they were highly miniaturized ... each diode is one of the seven light emitting bar !



*Liquid Cristal Display* (LCD) are much more efficient, because they DO NOT consume current ...





A simple black or white LCD display works by either allowing daylight to be reflected back out at the viewer or preventing it from doing so, in which case the viewer sees a black area. The liquid crystal is the part of the system that either prevents light from passing through it or not.

The crystal is placed between two polarising filters that are at right angles to each other and together block light. When there is no electric voltage applied to the crystal, it twists light by 90°, which allows the light to pass through the second polariser and be reflected back. But when the voltage is applied, the crystal molecules align themselves, and light cannot pass through the polariser: the segment turns black. Selective application of voltage to electrode segments creates the digits we see.





TFT LCD display

### **Electronic and Digital Counters:**

$N = k_n x^n + k_{n-1} x^{n-1} + \dots + k_1 x^1 + k_0 x^0 + k_{-1} x^{-1} + \dots$	Ge	neric way of <u>exploding</u> the <u>representation of a number</u> !
$8725,4 = 8 \cdot 10^3 + 7 \cdot 10^2 + 2 \cdot 10^1 + 5 \cdot 10^0 + 4 \cdot 10^{-1}$	exampl	le of a number <i>N</i> = 8725,4 expressed in <i>decadic base</i>
$19 = 1 \cdot 2^4 + 0 \cdot 2^3 + 0 \cdot 2^2 + 1 \cdot 2^1 + 1 \cdot 2^0$	example of a number N = 19 expressed in <b>binary base</b> in summary form: 10011	
$147 = 1 \cdot 2^7 + 0 \cdot 2^6 + 0 \cdot 2^5 + 1 \cdot 2^4 + 0 \cdot 2^3 + 0 \cdot 2^2 + 1 \cdot 2^1$	$+1 \cdot 2^{0}$	example of a number <i>N</i> = 147 expressed in <i>binary base</i> in summary form: 10010011

It is easily seen, that in *binary format* the "coefficients" that are needed (the <u>binary digits</u> : **bit**) increase rapidly ! A **bit** is an <u>elementary information carrier</u> !

However, in the *electronic measurement instrumentation* a special code system is employed: the <u>**BCD code</u>** (*Binary Coded Decimal*) which encodes in binary the *individual decimal digits* !</u>

This is a pure binary code that encodes the *ten digits from 0 to 9* with a <u>four bit</u> configuration ... Remember : with "*n* bits" we can count in binary up to  $2^n - 1$ 

Decimal Digit	Four-Bit Binary Equivalent	Binary-Coded Decimal Equivalent
0	0000	0000
1	0001	0001
2	0010	0010
3	0011	0011
4	0100	0100
5	0101	0101
6	0110	0110
7	0111	0111
8	1000	1000
9	1001	1001
10	1010	Illegal
11	1011	Illegal
12	1100	Illegal
13	1101	Illegal
14	1110	Illegal
15	1111	lllegal

The fundamental basic element for the *electronic counting* is the *astable electronic multivibrator* (*FLIP – FLOP*)

The **FF** changes status when it receives a trigger at its input, and "keeps the new status" until a new trigger is received at the input of the device:

Note on the left table: 4 bits = we count up to  $2^4 - 1$ 



Basic flip-flop circuit.



A Flip – Flop (FF) together with a CR circuit and a rectifier diode is the "elementary circuit" of the BCD counter :



Note that for every <u>two triggers</u> <u>at the circuit input</u>, we have <u>only</u> <u>one trigger at the output</u> ! The circuit <u>divides by two</u> the electric triggers received at its input !

If we connect *four of these elementary cells* in series, we have designed the electronic circuit that <u>counts in the</u> <u>BCD code a single digit</u> (from 0 to 9) :



Indicators L tell if the FF is in the *High* (X) or *Low* (O) status

*n* is the number of triggers received at the input !



Note that, to get one trigger at the output we need 16 input triggers ... after that, the counter resets to zero again.

We recognize that the 4 Flip Flop  $(I_1 \ I_2 \ I_4 \ I_8)$  are the *elementary* (*digital*) *memory cells* which change the "combination of their status" depending on how many triggers are inputted to the device. The four cells count in binary code:



LSB = Least Significant Bit MSB = Most Significant Bit

0

examples:	6 = 0 1 1 0	
	11 = 1 1 0 1	
	14 = 0 1 1 1	

However, to realize the **BCD counter**, we need the counter to count only up to 9 therefore, the remaining numbers (10 to 15) must be assigned *illegal value* ... and to realize a decimal counter, we need also one trigger to be outputted every ten input triggers !

To obtain this result, we have to modify the electronic circuit, <u>speeding up the trigger output</u> by "sending some extra triggers" at the input with a double feedback:



Unità di conteggio decimale

#### **Time and Frequency Measurement:**



The <u>clock</u> is an *electronic oscillator* with a "fairly high" frequency (100 MHz) and is always on.

The gate control opens and closes the gate depending on the input signal level. The triggers produced by the clock pass through the gate and are counted (n) by the BCD counter only during the period of time (t) for which the gate is open:

$$t = \frac{n}{f_{CLK}} = \frac{107153}{10^8 Hz} = 0.00107153 \ s$$

If we connect to the *BCD counter* an <u>electronic</u> <u>gate</u>, a <u>quartz clock</u>, an <u>event input amplifier</u> <u>with a gate control</u>, we can measure with *high resolution* the time between two events:



## Analog to Digital (A/D) Conversion:

*Electronic and Digital Counters* are fundamental devices for <u>Analog to Digital</u> and <u>Digital to Analog Conversion</u>



Analog and discrete representations of a time-varying signal.



Sampling a signal means to "extract" from the analog continuous voltage signal a <u>certain</u> <u>number of voltage values (the samples)</u>, measured each other at a <u>regular time distance</u> (the sampling period) !

Sampling a signal is always a loss of information !

The inverse of the sampling period is the **sampling frequency**:  $f_c = 1/T_c$ 

If the sampling frequency is not "chosen carefully" the information of the analog measured signal can be completely spoiled !

The "sampling" procedure is done by special electronic devices called <u>A/D Converters</u>

Today there are many different types of *A/D converters* employed in so many *appliances of consumer electronics*. We will study the three most important *A/D converters for measurement instruments* :



The *integrating converter* or *voltage to time converter* is the device which equips all the bench digital voltmeters in the laboratory !

The analog signal  $v_i$  must be <u>kept constant</u> for all the time of the conversion; this task is performed by an external device the **sample and hold circuit** :



The <u>logic unit</u> connects the constant input signal  $v_i$  to the integrator for a predefined time *T*, the output voltage  $v_o$  will be:

$$V_{o} = -\frac{1}{CR} \int_{0}^{T} V_{i} dt = -\frac{V_{i}}{CR} \int_{0}^{T} dt = -\frac{V_{i} \cdot T}{CR} = -\frac{T}{CR} \cdot V_{i}$$

After the fixed time T, the logic unit switches the integrator input to an internal signal  $-v_r$ , always of the opposite sign of the input signal. Both signals  $v_i$  and  $-v_r$  are constant and produce two ramps at the integrator output  $v_o$  ...



Dual-ramp analog voltage to digital conversion.

The integrator output voltage  $v_o$  at time T reflects the charge the capacitor C has physically accumulated during that time, which is also the charge the same capacitor releases during the time  $t_m$  of the descending ramp:  $Q = V_i \cdot T = -V_r \cdot t$ 

Therefore:  $V_i = -\frac{V_r}{T} \cdot t$ 

which is the <u>characteristic</u> <u>curve</u> of the device !

Because  $v_r$  and T are constant for every input signal  $v_i$ , the signal  $v_i$  is simply proportional to the measured time  $t_m$  which, in fact, is different for each input voltage  $v_{i1}$ ,  $v_{i2}$ , ... The time  $t_m$  is measured by the <u>digital counter</u>, starting when the logic unit connects the internal reference signal and stopping when the "comparator signals to the logic unit" the integrator output  $v_o$  has crossed zero !

The *sampling period* is at least :  $T + t_m$ 

Another **A/D Converter**, employed in the <u>digital acquisition systems</u>, is the <u>successive approximation converter</u> : A 4 bit example is shown in the figure here below:



This converter is based on the <u>summing</u> <u>Operational Amplifier</u> and the working principle is based on comparing the input signal  $v_i$  with "successively added" internal reference voltages.

The logic unit operates successively on the switches  $\boldsymbol{b}_i$  with i = 1, 2, ... 4, which can assume the value **1** (close) or **0** (open).

The characteristic curve of the device is therefore:

$$V_o = R\left(\frac{b_1}{R} + \frac{b_2}{2R} + \frac{b_3}{4R} + \frac{b_4}{8R}\right) \cdot V_r = V_r\left(b_1 + \frac{b_2}{2} + \frac{b_3}{4} + \frac{b_4}{8}\right) \frac{R}{R} = V_r\left(b_1 + \frac{b_2}{2} + \frac{b_3}{2^2} + \frac{b_4}{2^3}\right)$$

The procedure goes step by step, as in the next example :



The input unknown signal to the device is  $V_i$ at the beginning of the conversion, all switches are open

the characteristic curve is :  $V_o = V_r \left( b_1 + \frac{b_2}{2} + \frac{b_3}{2^2} + \frac{b_4}{2^3} \right)$ 

the logic unit closes  $b_1$ : it results  $V_i > V_1$  the switch *remains <u>close</u>:*  $b_1 = 1$ the logic unit closes  $b_2$ : it results  $V_i < V_2$  the switch *will be <u>reopened</u>:*  $b_2 = 0$ the logic unit closes  $b_3$ : it results  $V_i > V_3$  the switch *remains <u>close</u>:*  $b_3 = 1$ the logic unit closes  $b_4$ : it results  $V_i > V_4$  the switch *remains <u>close</u>:*  $b_4 = 1$ 

where  $V_k$  k = 1...4 is the summing OA output voltage at each step.

At the end of the "successive approximations" procedure we get :

 $V_o = V_4 = V_r \left( 1 + \frac{0}{2} + \frac{1}{2^2} + \frac{1}{2^3} \right) = \frac{11}{8} V_r$  and the corresponding **binary code** is "1 0 1 1"

Note that the last step  $V_o = V_4 \neq V_i$  ! There is a **discretization error** 

 $\varepsilon_d = V_i - V_4$ 

The discretization error is due to the limited number of switches (**bits**) of the A/D converter, in fact the <u>resolution</u> of the device is equal to the LSB :  $V_{FS}/2^4 = 2V_r/16$ 

Discretization error can be minimized only adding more bits (switches) to the A/D converter ! Modern A/D converter have at least 12 bits or 16 bits, which means  $2^{16} - 1 = 65.536$  discretization levels !

Note also that *successive approximation converters* always <u>approximate by defect</u> the analog value, and to mitigate this problem <u>the characteristic curve is shifted ½ LSB to the left</u>, as shown below for a 3 bit converter :



The figure show also another unavoidable error the A/D converters do, the <u>saturation error</u>: when all the bits (switches) are set to 1 the approximated output value is  $\frac{7/8 \text{ of the Full Scale voltage}}{1 \text{ or } range}$  or  $\frac{range}{1 \text{ FS}} = 2V_{ref}$ . This problem can be solved only by increasing the range of the A/D converter !

Successive approximation A/D converters have a fixed machine time to do the conversion therefore, the **sampling period** is dependent only on the number of successive approximations (*bits*) and is relatively short (a few  $\mu s$ ), which makes this A/D converter a relatively fast device !

The velocity of conversion is directly related to the **dynamic response** of such devices : If the conversion procedure is fats, the <u>sampling period  $T_s$  can be short</u> and the <u>sampling frequency  $f_s$  can be high</u> !

The <u>Nyquist sampling theorem</u> states that the sampling frequency of the A/D converter must be at least double of the highest frequency of the signal :  $f_s \ge 2f_{Max}$ If this rule is not observed, the discrete signal will be affected by <u>aliasing</u>:



Be advised that, to have a <u>good digital</u> <u>reconstruction of the analog waveform</u>, it is good practice to use a sampling frequency at leest 10 times higher than the signal highest frequency !

$$f_s \geq 10 f_{Max}$$



The fastest A/D converter employed in measurement instrumentation (digital oscilloscopes) is the FLASH converter :



The 3 bit example in the figure has  $2^3 - 1 = 7$  comparators in the circuit.

The resistor network operates a "multiple voltage partition" from the *full range*  $V_r$  to *zero*, which are also the *quantization levels* of the device. The comparators put to 0 (**low**) the output if the input signal  $V_i$  is lower than the partitioned inner reference voltage  $V_r$  or to 1 (**high**) if the input signal  $V_i$ is higher than the corresponding partitioned voltage !

The comparators work in parallel and achieve all together the comparison. The <u>codifying network</u> reconstructs the binary code for the corresponding *input voltage level* !

Flash comparators are *incredibly fast* (<u>sampling period lower</u> <u>than 1 µs</u>) but are increasingly complicate when the number of bits increase: an <u>8 bit comparator requires  $2^8 - 1 = 255$ </u> <u>comparators inside</u>.

#### Scheme of a modern digital data acquisition system



*Electronics* and *Information and Communication Technologies* have deeply entered the measurement world, leaving to physics only the first stage of the measurement chain: the *transducer*, the only one in strict contact with the *measurand* ...